



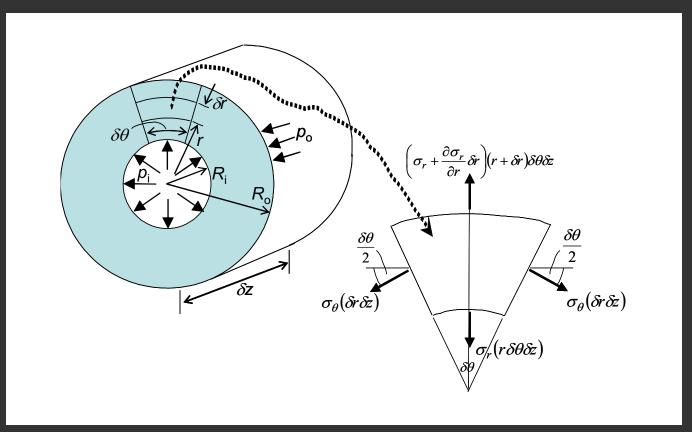
# **Analysis of Thick Cylinders**

- Thick cylinder problems are statically indeterminate
  - In order to obtain a solution, it is necessary to consider:
    - Equilibrium,
    - Compatibility
    - Material behaviour (stress-strain relationship)

#### <u>Assumptions</u>

- i. Plane transverse sections remain plane (this is true remote from the ends)
- ii. Deformations are small
- iii. The material is linear elastic, homogenous and isotropic.

#### Equilibrium



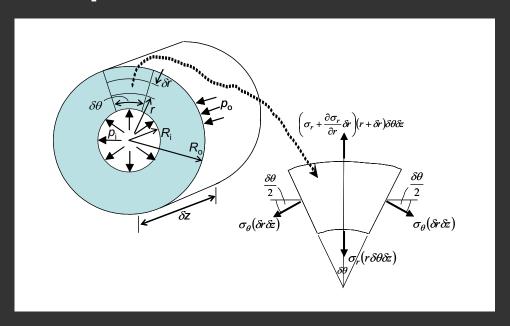
r,  $\theta$ , z coordinate system

 $\sigma_r$  = radial stress

 $\sigma_{\theta}$  = hoop stress

 $\sigma_z$  =axial stress

#### Equilibrium

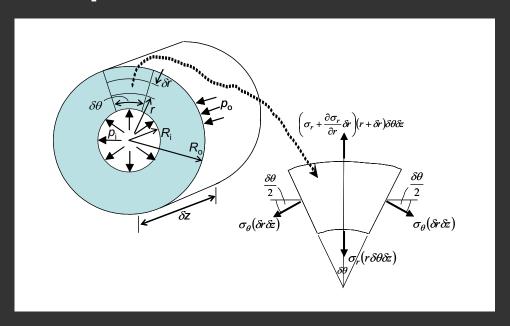


$$\left(\sigma_r + \frac{d\sigma_r}{dr}\delta r\right)(r + \delta r)\delta\theta\delta z = \sigma_r(r\delta\theta\delta z) + 2\sigma_\theta(\delta r\delta z)\sin\left(\frac{\delta\theta}{2}\right) \tag{1}$$

For small  $\delta\theta$ ,  $\sin\left(\frac{\delta\theta}{2}\right) \approx \frac{\delta\theta}{2}$  therefore:

$$\sigma_r(r+\delta r)\delta\theta + \frac{d\sigma_r}{dr}\delta r(r+\delta r)\delta\theta = \sigma_r r\delta\theta + \sigma_\theta \delta r\delta\theta$$

#### Equilibrium

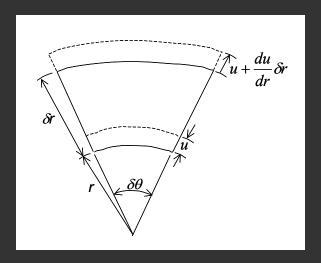


$$r\sigma_r + \sigma_r \delta r + r \frac{d\sigma_r}{dr} \delta r + \frac{d\sigma_r}{dr} \delta r^2 = \sigma_r r + \sigma_\theta \delta r \tag{2}$$

As 
$$\delta r \to 0$$
,  $\frac{d\sigma_r}{dr} \delta r^2 \to 0$ 

$$\sigma_{\theta} - \sigma_{r} = r \frac{d\sigma_{r}}{dr} \tag{3}$$

#### Compatibility



$$\varepsilon = \frac{\text{extension}}{\text{original length}}$$

Hoop strain, 
$$\varepsilon_{\theta} = \frac{(r+u)\delta\theta - r\delta\theta}{r\delta\theta} = \frac{u}{r}$$
 (4)

Radial strain, 
$$\varepsilon_r = \frac{\left(u + \frac{du}{dr}\delta r\right) - u}{\delta r} = \frac{du}{dr}$$
 (5)

Axial strain, 
$$\varepsilon_z = \text{constant}$$
 (6)

- Material Behaviour
- Generalised Hooke's Law

$$\varepsilon_{\theta} = \frac{1}{E} (\sigma_{\theta} - \nu(\sigma_r + \sigma_z)) \tag{7}$$

$$\varepsilon_r = \frac{1}{E}(\sigma_r - \nu(\sigma_\theta + \sigma_z)) \tag{8}$$

$$\varepsilon_{z} = \frac{1}{E} (\sigma_{z} - \nu(\sigma_{r} + \sigma_{\theta})) \tag{9}$$

(assuming linear elastic, isotropic material behaviour)

- Equations (3) to (9) have seven unknowns,
- i.e. u,  $\sigma_{\theta}$ ,  $\sigma_{r}$ ,  $\sigma_{z}$ ,  $\varepsilon_{\theta}$ ,  $\varepsilon_{r}$ ,  $\varepsilon_{z}$ , which are all functions of r,  $p_{o}$ ,  $p_{i}$ ,  $R_{o}$ ,  $R_{i}$ , v and E.
- Substituting  $u = r\varepsilon_{\theta}$  from Eq. (4) into Eq. (5) gives

$$\varepsilon_r = \frac{d}{dr}(r\varepsilon_\theta)$$

$$\varepsilon_r = \varepsilon_\theta + r \frac{d\varepsilon_\theta}{dr}$$
 (a)

• Using Eq. (7) and Eq. (8) in Eq. (a) gives

$$\frac{1}{E} \left( \sigma_r - \nu (\sigma_\theta + \sigma_z) \right) = \frac{1}{E} \left( \sigma_\theta - \nu (\sigma_r + \sigma_z) \right) + \frac{r}{E} \left( \frac{d\sigma_\theta}{dr} - \nu \frac{d\sigma_r}{dr} - \nu \frac{d\sigma_z}{dr} \right)$$

$$(1+\nu)\sigma_r = (1+\nu)\sigma_\theta + r\frac{d\sigma_\theta}{dr} - r\nu\frac{d\sigma_r}{dr} - r\nu\frac{d\sigma_z}{dr}$$
 (b)

• Using Eq. (6)  $\frac{\mathrm{d}\varepsilon_z}{\mathrm{d}r} = 0$  then Eq. (9) gives

$$0 = \frac{d\sigma_z}{dr} - \nu \frac{d\sigma_r}{dr} - \nu \frac{d\sigma_\theta}{dr}$$

$$\frac{d\sigma_z}{dr} = \nu \frac{d\sigma_r}{dr} + \nu \frac{d\sigma_\theta}{dr}$$
(c)

• Substituting (c) in (b)

$$(1+\nu)\sigma_r = (1+\nu)\sigma_\theta + r\frac{d\sigma_\theta}{dr} - r\nu\frac{d\sigma_r}{dr} - r\nu^2\frac{d\sigma_r}{dr} + r\nu^2\frac{d\sigma_\theta}{dr}$$

$$(1+\nu)\sigma_r = (1+\nu)\sigma_\theta + r(1-\nu^2)\frac{d\sigma_\theta}{dr} - r\nu(1+\nu)\frac{d\sigma_r}{dr}$$

$$\sigma_{\theta} - \sigma_{r} = rv \frac{d\sigma_{r}}{dr} - (1 - v) \frac{d\sigma_{\theta}}{dr}$$
 (d)

Substituting the right hand side from Eq. (d) into Eq. (3) gives:

$$rv\frac{d\sigma_r}{dr} - (1 - v)\frac{d\sigma_\theta}{dr} = r\frac{d\sigma_r}{dr}$$

$$r(1-\nu)\left[\frac{d\sigma_r}{dr} + \frac{d\sigma_\theta}{dr}\right] = 0$$

$$\frac{d}{dr}(\sigma_r + \sigma_\theta) = 0$$

Integration leads to:

$$\sigma_r + \sigma_\theta = 2A$$
 (e)

Where A is a constant of integration

Again using Eq. (3) and substituting for  $\sigma_{\theta}$  gives:

$$2\sigma_r = 2A - r\frac{d\sigma_r}{dr}$$

Rearranging

$$r\frac{d\sigma_r}{dr} + 2\sigma_r = 2A$$

Which is equivalent to

$$\frac{1}{r}\frac{d}{dr}(r^2\sigma_r) = 2A$$

$$r^2\sigma_r = \frac{2Ar^2}{2} - B$$

Where B is another constant of integration, which leads to:

$$\sigma_r = A - rac{B}{r^2}$$
 and using Eq. (e) leads to  $\sigma_{ heta} = A + rac{B}{r^2}$ 

$$\sigma_{\theta} = A + \frac{B}{r^2}$$

## **Analysis of Thick Cylinders**

• The hoop and radial stresses at any point (radius, r) in the wall cross-section of a thick cylinder can be determined using Lame's equations:

$$\sigma_r = A - \frac{B}{r^2}$$

$$\sigma_{\theta} = A + \frac{B}{r^2}$$

- Where A and B are Lame's constants (constants of integration)
- Note that, since  $\varepsilon_z = {\rm const}$  and  $\sigma_r + \sigma_\theta = {\rm const}$ , then Eq. (9) shows that  $\sigma_z = {\rm const}$ , i.e. it is independent of r. The value of  $\sigma_z$  can therefore be obtained from a consideration of axial equilibrium.

### **Learning Objectives**

1. Appreciate the difference between the stress analysis of thin and thick cylinders (knowledge);



 Understand the derivation of Lame's equations (comprehension);



- Determine the stresses in a thick walled cylinder subjected internal and external pressure (application);
- 4. Determine the stresses caused by shrink fitting a cylinder onto another (application);
- 5. Be able to include 'inertia' effects into the thick cylinder equations to calculate the stresses in a rotating disc (application).